

# **Aerosol Particle Size Distribution retrieval from multiwavelength lidar signals**

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**3rd International Workshop on Optoelectronic Techniques for Environmental Monitoring,  
30 IX – 2 X, 2009 Bucharest, Romania**

# Aerosol Particle Size Distribution

## APSD $n(r,z)$

$$n(r, z) = \frac{dN}{dr}$$

N – particle number  
r – radius  
z - distance

## Extinction coefficient

$$\alpha_{\lambda}(z) = \int_0^{\infty} \pi r^2 n(r, z) Q^E(\lambda, r) dr$$

$Q^B$  - backscatter efficiency  
 $Q^E$  - extinction efficiency

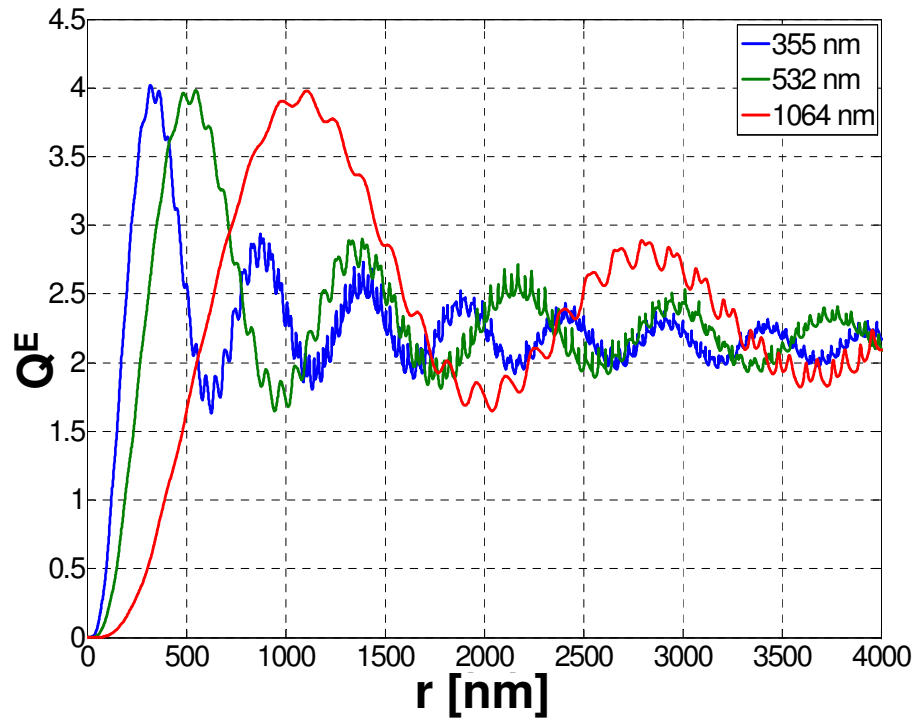
## Backscattering coefficient

$$\beta_{\lambda}(z) = \int_0^{\infty} \pi r^2 n(r, z) Q^B(\lambda, r) dr$$

$$r_{eff}(z) = \frac{\int r^3 n(r, z) dr}{\int r^2 n(r, z) dr}$$

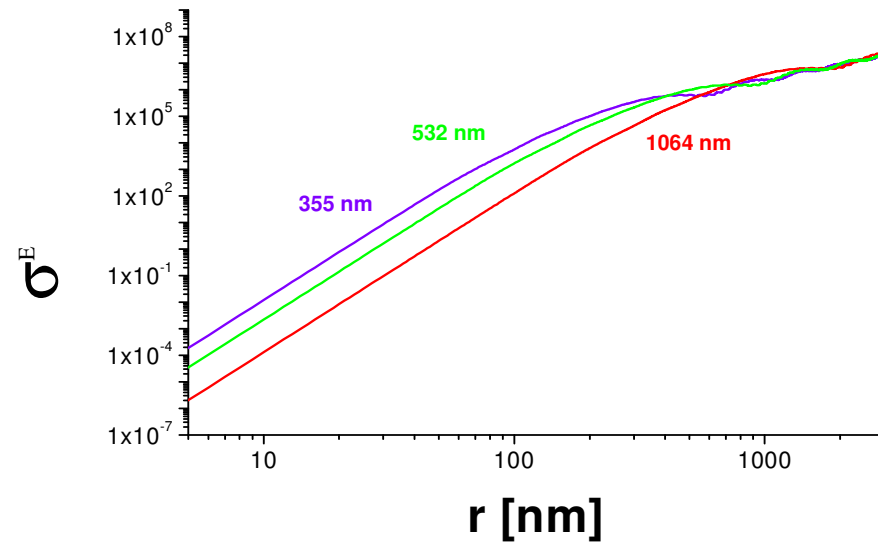
# Mie-Lorenz scattering

## extinction efficiency



$$Q = \frac{\sigma}{\pi r^2}$$

## extinction cross section $\sigma_E$



# Lidar signal elaboration

$$S(z) = \frac{A}{z^2} \cdot \beta(z) \exp\left[-2 \int_0^z \alpha(x) dx\right]$$



$$L(z) = S(z) \cdot z^2 = A \cdot \beta(z) \exp\left[-2 \int_0^z \alpha(x) dx\right]$$

A - lidar (apparatus) constant  
z - distance  
 $\alpha$  - extinction coefficient  
 $\beta$  - backscatter coefficient

## 1. Range corrected lidar signals

$$L(z, \lambda_1) = A(\lambda_1) \beta(z, \lambda_1) \exp\left[-2 \int_{z_0}^z \alpha(x, \lambda_1) dx\right]$$

...

$$L(z, \lambda_k) = A(\lambda_k) \beta(z, \lambda_k) \exp\left[-2 \int_{z_0}^z \alpha(x, \lambda_k) dx\right]$$

# Lidar signal elaboration

$$L(z, \lambda_1) = A(\lambda_1) \beta(z, \lambda_1) \exp \left[ -2 \int_{z_0}^z \alpha(x, \lambda_1) dx \right]$$

...

$$L(z, \lambda_k) = A(\lambda_k) \beta(z, \lambda_k) \exp \left[ -2 \int_{z_0}^z \alpha(x, \lambda_k) dx \right]$$

## 2. Ratio of signals from neighbouring distances

$$\frac{L_\lambda(z_{l+1})}{L_\lambda(z_l)} = \frac{\beta_\lambda(z_{l+1})}{\beta_\lambda(z_l)} \exp \left\{ -\Delta z [\alpha_\lambda(z_l) + \alpha_\lambda(z_{l+1})] \right\}$$

Cost function

$$\chi^2(z_l) = \sum_{\lambda=1}^{\Lambda} \left( \frac{L_\lambda(z_{l+1})}{L_\lambda(z_l)} - \frac{\beta_\lambda(z_{l+1})}{\beta_\lambda(z_l)} \exp \left\{ -\Delta z [\alpha_\lambda(z_l) + \alpha_\lambda(z_{l+1})] \right\} \right)^2$$

## **3.** Substitution of $\alpha$ and $\beta$ coefficients...

$$\beta_\lambda(z) = \int_0^\infty \pi r^2 n(r, z) Q^B(\lambda, r) dr \qquad \alpha_\lambda(z) = \int_0^\infty \pi r^2 n(r, z) Q^E(\lambda, r) dr$$

... the unknown -  $n(r, z)$  (no lidar ratio)

## 4. $n(r, z)$ is found with minimization technique

$$n(r, z)$$

# Assumptions

- **APSD** as two mode distribution, each mode – in **log-normal** form

$$n(r, z) = \frac{N(z)}{\sqrt{2\pi} \cdot \log \sigma(z)} \cdot \frac{1}{r} \cdot \exp \left\{ -\frac{[\log r - \log r_m(z)]^2}{2 \cdot \log^2 \sigma(z)} \right\}$$

N – number concentration  
 $\sigma$  - standard deviation  
 $r_m$  – modal radius

- spherical droplets
- known refractive index (water, salt)
- coefficients of backscattering  $\beta$  and extinction  $\alpha$  calculated with Mie theory

steps

Parameters' ranges

$$70 < N_1 < 9000,$$

$$50 < r_{m_1} < 240,$$

$$1.5 < \sigma_1 < 2.7;$$

$$0.15 < N_2 < 52,$$

$$230 < r_{m_2} < 1600,$$

$$1.5 < \sigma_2 < 2.7;$$

Distribution

$\sigma \sim 2$

$$n(r, z) = \frac{N_1(z)}{\sqrt{2\pi} \cdot \log \sigma_1(z)} \cdot \frac{1}{r} \cdot \exp \left\{ -\frac{[\log r - \log r_{m_1}(z)]^2}{2 \cdot \log^2 \sigma_1(z)} \right\} + \frac{N_2(z)}{\sqrt{2\pi} \cdot \log \sigma_2(z)} \cdot \frac{1}{r} \cdot \exp \left\{ -\frac{[\log r - \log r_{m_2}(z)]^2}{2 \cdot \log^2 \sigma_2(z)} \right\}$$

Scattering coefficients

$$\beta_\lambda(z) = \int_0^\infty \pi r^2 n(r, z) Q^B(\lambda, r) dr$$

$$\alpha_\lambda(z) = \int_0^\infty \pi r^2 n(r, z) Q^E(\lambda, r) dr$$

$$\frac{L(z_{l+1})}{L(z_l)} =$$

$$= \frac{\beta_\lambda(z_{l+1})}{\beta_\lambda(z_l)} \exp \{ -\Delta z [\alpha_\lambda(z_l) + \alpha_\lambda(z_{l+1})] \}$$

measured

calculated

best fits selected

# Multiwavelength lidar

## Optical sender:

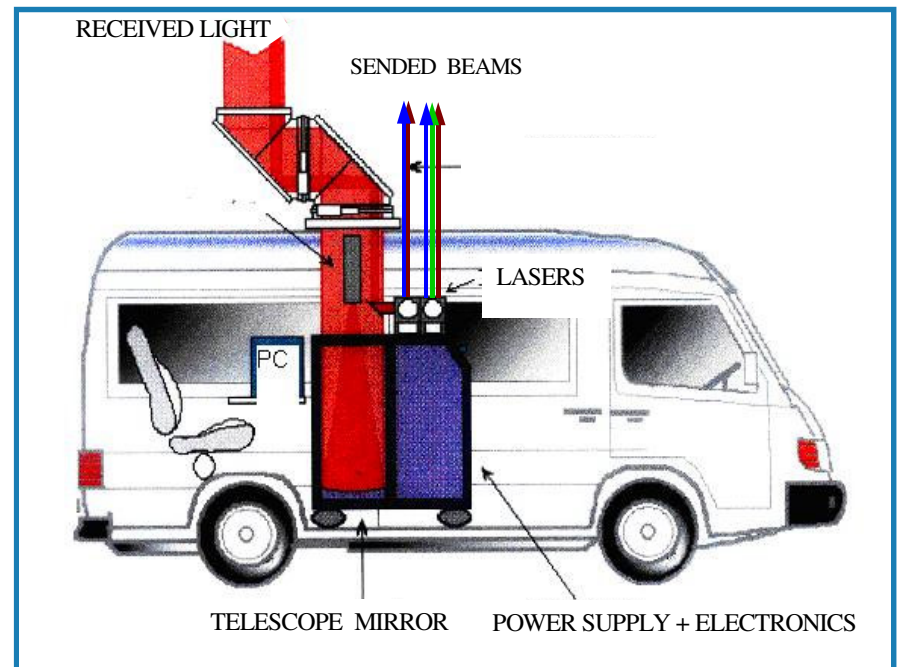
\* pulsed laser:

Nd:YAG - 1064, 532, 355 nm;

E of the light pulses ~ 200, 100, 60 mJ,  
repetition rate ~ 10 Hz.

## Optical receiver:

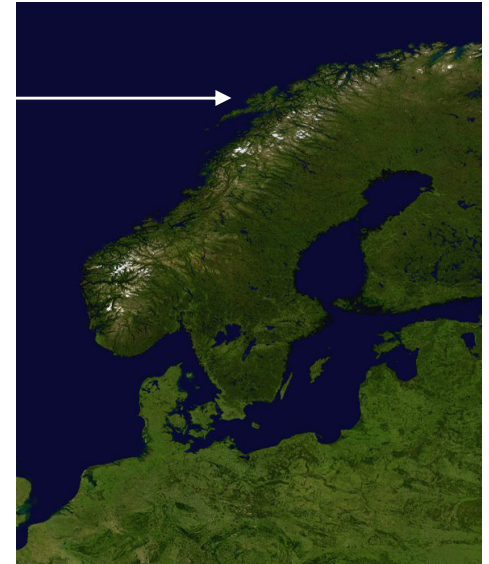
- \* Newtonian telescope  
(mirror ~ 400 mm in diameter,  
focal length = 1200 mm),
- \* 3-channel polychromator,
- \* 12-bits A/D converters (50 MHz)



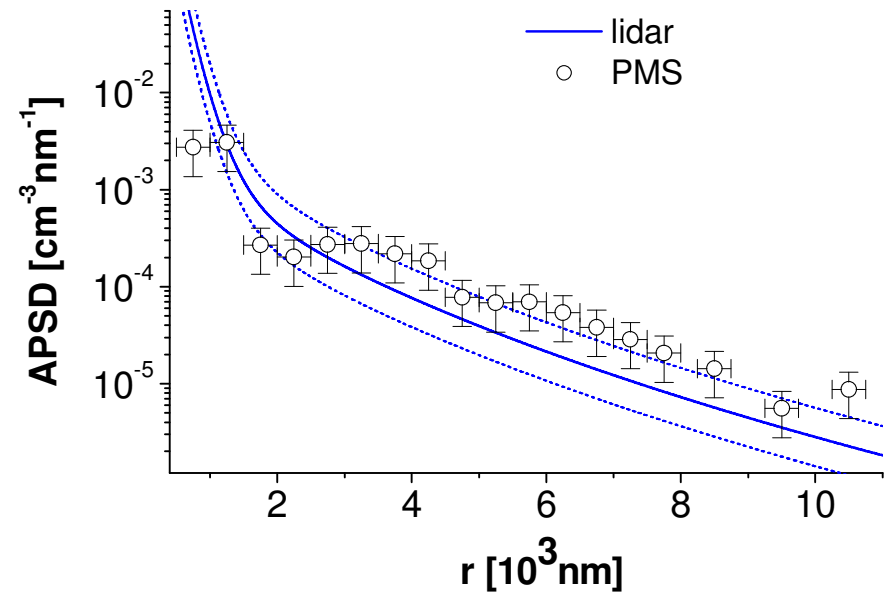
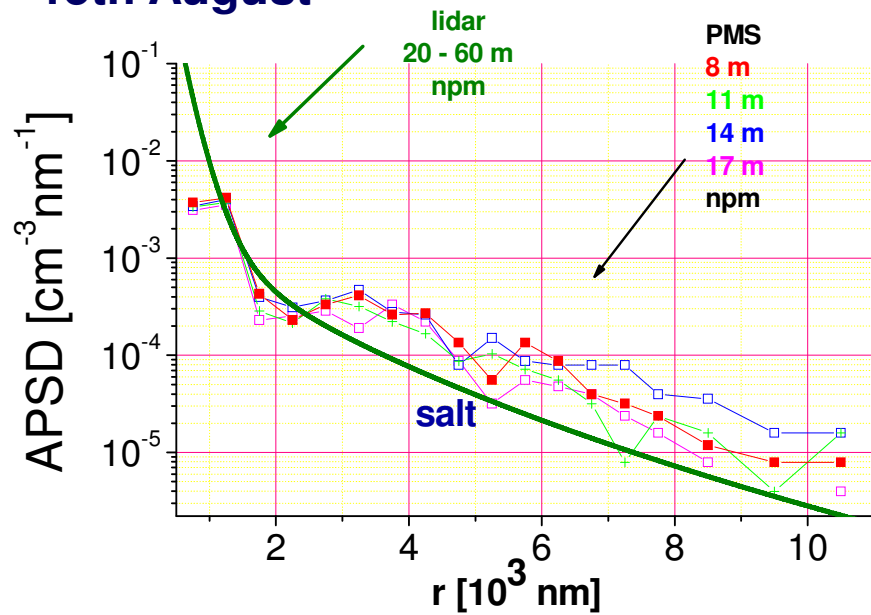


# marine aerosol

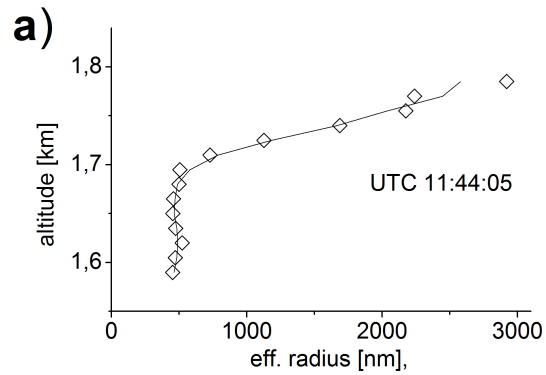
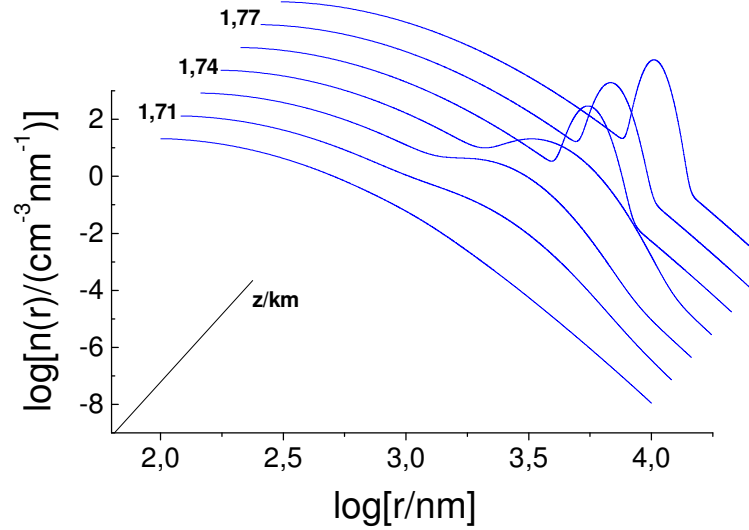
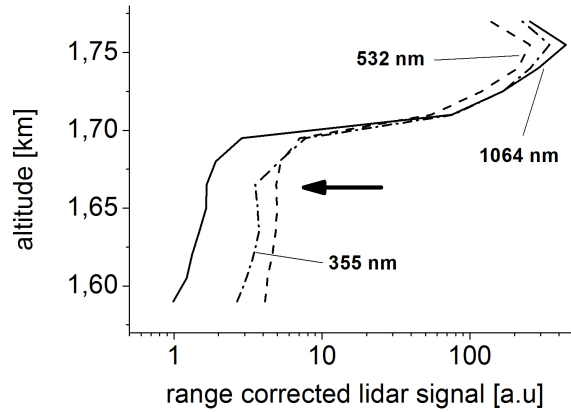
Arctic Lidar Observatory for Middle Atmosphere Research (ALOMAR),  
Andoya, Norway, July/August 2007



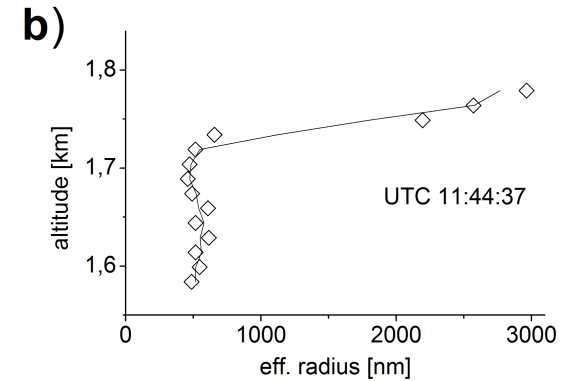
15th August



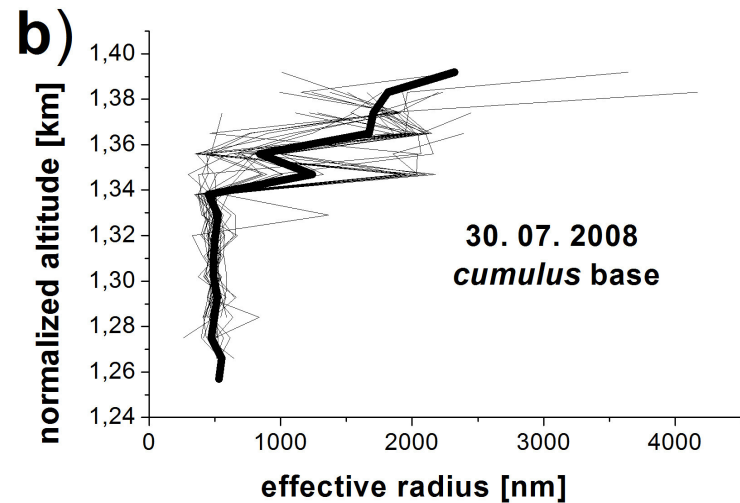
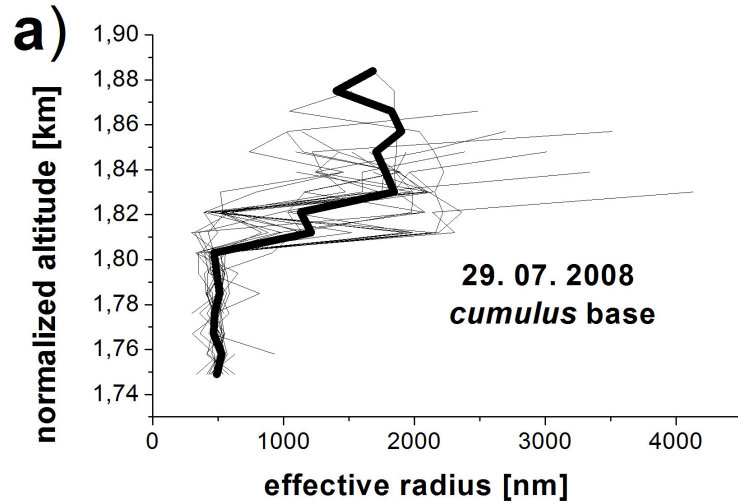
# aerosol under cumulus cloud - 2006



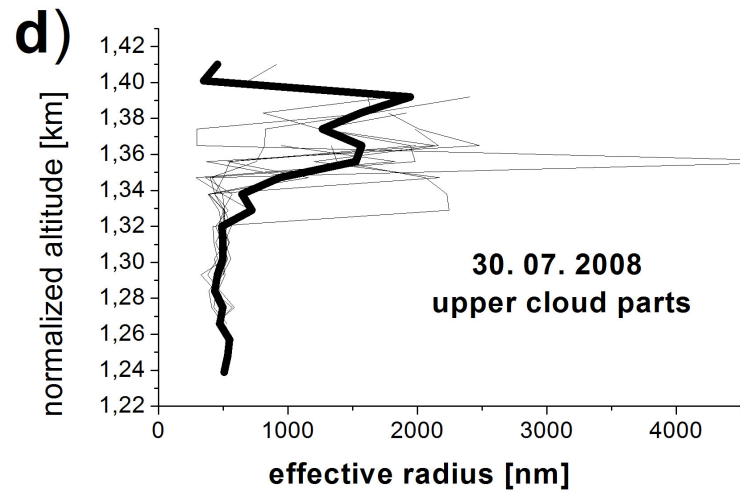
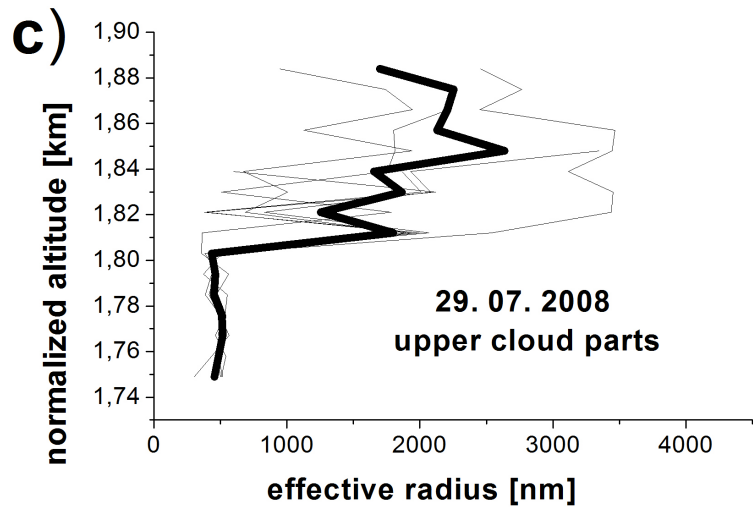
$$r_{eff}(z) = \frac{\int r^3 n(r, z) dr}{\int r^2 n(r, z) dr}$$



# aerosol under cumulus cloud - 2008



Normalized to reference height



# Summary

- method to determine aerosol particle size distribution from multiwavelength lidar signals was presented
  - assumed spherical shape and known refractive index of aerosol particles,
  - lidar ratio not necessary
- experimental test - comparison with PMS
- method used for data under cumuli base – results seem to confirm (qualitatively!) CCN activation and growth under the cloud base

*Thank You for attention*





Laser monitoring of air pollution

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